# Some infinite-dimensional simple Lie algebras in characteristic 0 related to those of Block 

Dragomir Ž. Đoković ${ }^{\mathrm{a}, *}$, Kaiming Zhao ${ }^{\mathrm{b}, 1}$<br>${ }^{\text {a }}$ Department of Pure Mathematics, University of Waterloo, Waterloo, Ont., Canada N2L 3 G1<br>${ }^{\mathrm{b}}$ Institute of Systems Science, Academia Sinica, Reijing, 100080, People's Republic of China

Communicated by C.A. Weibel; received 26 March 1996


#### Abstract

Given a nontrivial torsion-free abelian group $(A,+, 0)$, a field $F$ of characteristic 0 , and a nondegenerate bi-additive skew-symmetric map $\varphi: A \times A \rightarrow F$, we study the Lie algebra $\mathscr{L}(A, \varphi)$ over $F$ with basis $\left\{e_{x}: x \in A \backslash\{0\}\right\}$ and multiplication $\left[e_{x}, e_{y}\right]=\varphi(x, y) e_{x+y}$. We show that $\mathscr{L}(A, \varphi)$ is simple, determine its derivations, and show that the locally finite derivations $D$ have the form $D\left(e_{x}\right)=\mu(x) e_{x}, \mu \in \operatorname{Hom}(A, F)$. We describe all isomorphisms between two such algebras. Finally, we compute $H^{2}(\mathscr{L}, F)$. (C) 1998 Elsevier Science B.V. All rights reserved.


AMS Classification: Primary 17B40; 17B65; secondary 17B56; 17B68

## 1. Introduction

Let $F$ be a field of characteristic 0 and $A$ an abelian group. Let $L$ be the vector space over $F$ with basis consisting of all symbols $e_{x}, x \in A$. Define a bilinear multiplication in $L$ by

$$
\left(e_{x}, e_{y}\right) \rightarrow\left[e_{x}, e_{y}\right]:=f(x, y) e_{x+y}
$$

where $x, y \in A$ are arbitrary and

$$
f(x, y)=\varphi(x, y)+\alpha(x-y)
$$

[^0]for some skew-symmetric bi-additive function $\varphi: A \times A \rightarrow F$ and some additive function $\alpha: A \rightarrow F$. We denote the vector space $L$ with this algebra structure by $L(A, \varphi, \alpha)$.

When $\varphi \neq 0$ and $\alpha \neq 0$, this algebra was studied by Block [2] and in our previous paper [4]. In that case $L$ is a Lie algebra if and only if $\varphi=\alpha \wedge \beta$ for some additive function $\beta: A \rightarrow F$, i.e.,

$$
\varphi(x, y)=\alpha(x) \beta(y)-\alpha(y) \beta(x)
$$

Assume that $\operatorname{ker}(\alpha) \cap \operatorname{ker}(\beta)=0$ and $A \neq 0$. In that case the Lie algebra $L=$ $L(A, \rho, \alpha)$ is close to being simple. More precisely, the derived algehra $I^{2}=[I, L]$ is either equal to $L$ or has codimension 1 in $L$, the center $Z$ of $L$ is either 0 or has dimension $1, Z \subset L^{2}$, and the quotient algebra $\mathscr{L}(A, \varphi, \alpha):=L^{2} / Z$ is simple. The algebras $\mathscr{L}(A, \varphi, \alpha)$ are called generalized Block algebras. In [4] we have determined the derivation algebra of $\mathscr{L}(A, \varphi, \alpha)$, described its automorphism group and computed its second cohomology group with coefficients in $F$.

In the special case when $\varphi=\alpha \wedge \beta$ and $\beta(A)=\mathbf{Z}$ one can define a proper simple subalgebra of $\mathscr{L}(A, \varphi, \alpha)$. These subalgebras were studied in detail in our paper [5].

If $\varphi=0$ and $\alpha \neq 0$, then $L$ is automatically a Lie algebra. In fact it is a special case of so called generalized Witt algebras. In this case $L$ is simple if and only if $\alpha$ is injective. For the properties of generalized Witt algebras (in characteristic 0 ), we refer the reader to our paper [6].

In the present paper we study the remaining case where $\varphi \neq 0$ and $\alpha=0$. Again $L(A, \varphi, 0)$ is a Lie algebra, and we simplify the notation by writing just $L(A, \varphi)$ instead of $L(A, \varphi, 0)$. Hence, we have

$$
\begin{equation*}
\left[e_{x}, e_{y}\right]=\varphi(x, y) e_{x+y} \tag{1.1}
\end{equation*}
$$

for all $x, y \in A$.
Let $K_{\varphi}$ be the kernel of $\varphi$, i.e., $K_{\varphi}$ is the subgroup of $A$ consisting of all $x \in A$ such that $\varphi(x, y)=0$ for all $y \in A$. The subspace $Z \subset L$ spanned by all $e_{x}$ with $x \in K_{\varphi}$ is the center of $L=L(A, \varphi)$. Let $\bar{A}=A / K_{\varphi}$ and let $\bar{\varphi}: \bar{A} \times \bar{A} \rightarrow F$ be the (skew-symmetric) bilinear map induced by $\varphi$. It is easy to check that

$$
L(A, \varphi) / Z \simeq L(\bar{A}, \bar{\varphi}) / F e_{\overline{0}}
$$

where $\overline{0}=0+Z \in \bar{A}$ and $F e_{\overline{0}}$ is the center of $L(\bar{A}, \bar{\varphi})$. Since we are interested only in studying the quotient algebra $L(A, \varphi) / Z$, the above isomorphism shows that, without any loss of generality, it suffices to consider the case where $K_{\varphi}=0$.

Hence, we assume from now on that $\varphi$ is non-degenerate (i.e., $K_{\varphi}=0$ ). Since $F$ has characteristic 0 , this assumption implies that $A$ is torsion-free. To avoid the trivial case, we assume also that $A \neq 0$. The condition $K_{\varphi} \neq 0$ implies that the rank of $A$ is at least 2 .

The one-dimensional subspace $F e_{0}$ is the center of $L(A, \varphi)$. The subspace

$$
\mathscr{L}(A, \varphi)=\sum_{x \in A \backslash\{0\}} F e_{x}
$$

is an ideal of $L(A, \varphi)$ and we have

$$
L(A, \varphi)=F e_{0} \oplus \mathscr{L}(A, \varphi)
$$

In Section 2 we show that the Lie algebra $\mathscr{L}(A, \varphi)$ is simple. In particular, it follows that $\mathscr{L}(A, \varphi)$ is the derived algebra of $L(A, \varphi)$. We mention that the finite-dimensional version of the simple Lie algebra $\mathscr{L}(A, \varphi)$, but now over a field of prime characteristic, has been introduced long ago by Albert and Frank in their paper [1]. The algebras $L\left(\mathbf{Z}^{n}, \varphi\right)$ in characteristic 0 were studied by Koepp in his Ph.D. thesis [7]. He showed that $\mathscr{L}\left(\mathbf{Z}^{n}, \varphi\right)$ is simple under an additional condition on $\varphi$. It follows from our simplicity theorem (Theorem 2.1) that the additional condition used by Koepp is not needed.

Note that $\mathscr{L}(A, \varphi)$ and $L(A, \varphi)$ are $A$-graded Lie algebras: the homogeneous component of $L(A, \varphi)$ of degree $x$ is $F e_{x}$. In Section 3 we describe the derivations of $\mathscr{L}(A, \varphi)$. In particular, we show that the derivations of degree $x \neq 0$ are inner, and that the derivations of degree 0 have the form $e_{x} \mapsto \mu(x) e_{x}$ where $\mu \in \operatorname{Hom}(A, F)$. The main result of that section is that the locally finite derivations of $\mathscr{L}(A, \varphi), \operatorname{rank}(A)<\infty$, are precisely the derivations of degree 0 .

In Section 4 we describe all isomorphisms between two simple algebras $\mathscr{L}(A, \varphi)$ and $\mathscr{L}(B, \psi)$ when $A$ and $B$ have finite ranks. As a consequence we obtain a description of the automorphism group of $\mathscr{L}(A, \varphi)$ when $A$ has finite rank.

Finally in Section 5 we compute the second cohomology group $H^{2}(\mathscr{L}, F)$ for the simple Lie algebra $\mathscr{L}=\mathscr{L}(A, \varphi)$.

More general Lie algebras (in characteristic 0 ) than the algebras studied in the present paper and [4] can be constructed by analogy with Block algebras in characteristic $p$ described in [3].

## 2. Simplicity of $\mathscr{L}(A, \varphi)$

As mentioned before, we assume that $A$ is a nonzero torsion-free abelian group and $\varphi: A \times A \rightarrow F$ is a nondegenerate skew-symmetric bi-additive map.

Theorem 2.1. The Lie algebra $\mathscr{L}(A, \varphi)$ is simple.
Proof. Let $I$ be a nonzero ideal of $\mathscr{L}=\mathscr{L}(A, \varphi)$. Let

$$
u=a_{1} e_{x_{1}}+\cdots+a_{n} e_{x_{n}}
$$

be a nonzero element of $I$, where $x_{1}, \ldots, x_{n} \neq 0$ and $a_{1}, \ldots, a_{n} \in F$, and assume that $u$ is chosen so that $n$ is minimal. It follows that the $x_{i}$ 's are distinct and the $a_{i}$ 's are all nonzero.

Assume that $n>1$. Let $y \in A$ be arbitrary and let $v=\left[u, e_{y}\right]$. Thus,

$$
\begin{equation*}
v=\varphi\left(x_{1}, y\right) e_{x_{1}+y}+\cdots+\varphi\left(x_{n}, y\right) e_{x_{n}+y} \in I . \tag{2.1}
\end{equation*}
$$

We claim that

$$
\begin{equation*}
\varphi\left(x_{1}-x_{2}, y\right)=0 \tag{2.2}
\end{equation*}
$$

If $\varphi\left(x_{1}, y\right)=0$, then (2.1) and the minimality of $n$ imply that also $\varphi\left(x_{2}, y\right)=0$, and so (2.2) holds. In particular, by taking $y=x_{1}$, we conclude that $\varphi\left(x_{1}, x_{2}\right)=0$.

If $\varphi\left(x_{1}, y\right) \neq 0$, then $v \neq 0$ and the minimality of $n$ implies that $\varphi\left(x_{i}, y\right) \neq 0$ for all $i$ 's. By replacing $u$ with $v$, we conclude that $\varphi\left(x_{1}+y, x_{2}+y\right)=0$. Since also $\varphi\left(x_{1}, x_{2}\right)=0$ and $\varphi$ is skew-symmetric and bi-additive, we conclude that (2.2) holds.

Since $\varphi$ is nondegenerate and (2.2) holds for all $y \in A$, we conclude that $x_{1}=x_{2}$, a contradiction. Hence $n=1$, i.e., $e_{x_{1}} \in I$.

We claim that $e_{y} \in I$ for all $y \neq 0$. If $\varphi\left(y, x_{1}\right) \neq 0$, then $y-x_{1} \neq 0$ and the claim follows from

$$
\left[e_{y-x_{1}}, e_{x_{1}}\right]=\varphi\left(y, x_{1}\right) e_{y} \in I
$$

Assume now that $\varphi\left(y, x_{1}\right)=0, y \neq 0, x_{1}$. Choose $z \in A$ such that $\varphi\left(z, x_{1}\right) \neq 0$ and $\varphi(y, z) \neq 0$. Since $\varphi\left(z, x_{1}\right) \neq 0$, we infer that $e_{z} \in I$. As $y \neq z$ and $\left[e_{y-z}, e_{z}\right]=$ $\varphi(y, z) e_{y} \in I$, we conclude again that $e_{y} \in I$. Thus our claim is proved.

So, we have $I=\mathscr{L}$, and $\mathscr{L}$ is simple.
In the case $A=\mathbf{Z}^{n}, n \geq 2$, the above theorem was proved by Koepp in his thesis [7], under the additional hypothesis:
(H) If $x_{1}, \ldots, x_{k} \in A$ are independent and $1 \leq k<n$, then there exists $y \in A$ such that $x_{1}, \ldots, x_{k}, y$ are also independent and $\varphi\left(x_{i}, y\right) \neq 0$ for some $i \in\{1, \ldots, k\}$.

Sincc $\varphi$ is assumed to be nondegenerate, the hypothesis (H) is automatically satisfied. Indeed, let $x_{1}, \ldots, x_{k} \in A$ be independent and $1 \leq k<n$. Assume that $\varphi\left(x_{i}, y\right)=0$ for all $i=1, \ldots, k$ whenever $y$ is chosen so that $x_{1}, \ldots, x_{k}, y$ are independent. Now assume that $x_{1}, \ldots, x_{k}, y$ are dependent and choose $z \in A$, such that $x_{1}, \ldots, x_{k}, z$ are independent. Then $\varphi\left(x_{i}, z\right)=0$ and $\varphi\left(x_{i}, y+z\right)=0$ for all $i$. We conclude that $\varphi\left(x_{i}, y\right)=0$ for all $i=1, \ldots, k$ and all $y \in A$. This means that $x_{1}, \ldots, x_{k} \in K_{\varphi}$, which contradicts the nondegeneracy of $\varphi$.

We conclude this section with an example of a simple Lie algebra $\mathscr{L}\left(\mathbf{Z}^{3}, \varphi\right)$.
Example 1. Let $A=\mathbf{Z}^{n}, n \geq 2$. A bi-additive skew-symmetric map $\varphi: A \times A \rightarrow F$ is given by a skew-symmetric $n$ by $n$ matrix over $F$, say the matrix $M$. Then $\varphi$ is nondegenerate (in our sense) if and only if

$$
M v=0 \Rightarrow v=0
$$

for all $v \in \mathbf{Z}^{n}$. Hence, $\varphi$ can be nondegenerate even if $\operatorname{det}(M)=0$.
For instance, if $n=3$ and

$$
M=\left(\begin{array}{rrr}
0 & a & b \\
-a & 0 & c \\
-b & -c & 0
\end{array}\right)
$$

with $a, b, c \in F$ linearly independent over $\mathbf{Q}$, then $\varphi$ is nondegenerate. In that case the Lie algebra

$$
\mathscr{L}(a, b, c):=\mathscr{L}\left(\mathbf{Z}^{3}, \varphi\right)
$$

is simple.

## 3. Derivations of $\mathscr{L}(A, \varphi)$

Let $D$ be a derivation of $\mathscr{L}=\mathscr{L}(A, \varphi)$. We extend $D$ to a derivation of $L=L(A, \varphi)$, and denote the extension again by $D$, by setting $D\left(e_{0}\right)=0$. For arbitrary $y \in A$ we have

$$
\begin{equation*}
D\left(e_{y}\right)=\sum_{x \in A} c(x, y) e_{x+y} \tag{3.1}
\end{equation*}
$$

for some scalars $c(x, y) \in F$. The scalars $c(x, y)$ satisfy the following condition:
(F) for each $y \in A$ there are only finitely many $x \in A$ such that $c(x, y) \neq 0$.

For each $x \in A$ we define the linear map $D_{x}: L \rightarrow L$ by

$$
\begin{equation*}
D_{x}\left(e_{y}\right)=c(x, y) e_{x+y}, \quad y \in A \tag{3.2}
\end{equation*}
$$

It is easy to verify that each $D_{x}$ is a derivation of $L$. Furthermore,

$$
\begin{equation*}
D=\sum_{x \in A} D_{x} \tag{3.3}
\end{equation*}
$$

in the sense that for each $y \in A$ only finitely many terms $D_{x}\left(e_{y}\right)$ are nonzero and

$$
D\left(e_{y}\right)=\sum_{x \in A} D_{x}\left(e_{y}\right)
$$

Since $D\left(e_{0}\right)=0$, we have

$$
\begin{equation*}
c(x, 0)=0, \quad \forall x \in A \tag{3.4}
\end{equation*}
$$

Since $D(\mathscr{L}) \subset \mathscr{L}$, we also have

$$
\begin{equation*}
c(x,-x)=0, \quad \forall x \in A \tag{3.5}
\end{equation*}
$$

Lemma 3.1. If $x \neq 0$, then $D_{x}$ is an inner derivation, i.e., $D_{x}=\lambda \operatorname{ad}\left(e_{x}\right)$ for some $\lambda \in F$.

Proof. As $x$ is fixed, we shall write $c_{y}$ instead of $c(x, y)$. By applying $D_{x}$ to $\left[e_{y}, e_{z}\right]=$ $\varphi(y, z) e_{y+z}$, we obtain

$$
\begin{equation*}
c_{y+z} \varphi(y, z)=c_{y} \varphi(x+y, z)+c_{z} \varphi(y, x+z) \tag{3.6}
\end{equation*}
$$

By replacing $z$ with $k y, k \in \mathbf{Z}$, we obtain

$$
\varphi(x, y) \cdot\left[c_{k y}-k c_{y}\right]=0
$$

Hence, if $\varphi(x, y) \neq 0$, then

$$
\begin{equation*}
c_{k y}=k c_{y}, \quad k \in \mathbf{Z} \tag{3.7}
\end{equation*}
$$

We now choose $y, z \in A$ such that $\varphi(x, y), \varphi(x, z)$, and $\varphi(x, y+z)$ are all nonzero. By replacing $y$ with $k y$ and $z$ with $k z$ in (3.6), we obtain that

$$
\begin{equation*}
k^{3} \varphi(y, z) \cdot\left[c_{y+z}-c_{y}-c_{z}\right]=k^{2}\left[\varphi(x, z) c_{y}-\varphi(x, y) c_{z}\right] \tag{3.8}
\end{equation*}
$$

holds for all integers $k$. We deduce that

$$
\begin{equation*}
\frac{c_{y}}{\varphi(x, y)}=\frac{c_{z}}{\varphi(x, z)} \tag{3.9}
\end{equation*}
$$

holds. We claim that (3.9) remains valid when we remove the restriction $\varphi(x, y+$ $z) \neq 0$.

Thus assume that $\varphi(x, y+z)=0$. We can choose $u \in A$ such that the numbers $\varphi(x, u), \varphi(x, y+u)$, and $\varphi(x, z+u)$ are nonzero. Consequently, we have

$$
\frac{c_{y}}{\varphi(x, y)}=\frac{c_{u}}{\varphi(x, u)}=\frac{c_{z}}{\varphi(x, z)}
$$

and so (3.9) holds.
Let $\lambda$ be the common value of all numbers $c_{y} \varphi(x, y)^{-1}$ with $\varphi(x, y) \neq 0$. Let $D^{\prime}=$ $D_{x}-\lambda \operatorname{ad}\left(e_{x}\right)$. For $y \in A$ such that $\varphi(x, y) \neq 0$ we have

$$
D^{\prime}\left(e_{y}\right)=D_{x}\left(e_{y}\right)-\lambda\left[e_{x}, e_{y}\right]=\left[c_{y}-\lambda \varphi(x, y)\right] e_{x+y}=0
$$

The elements $e_{y}$ such that $\varphi(x, y) \neq 0$ generate $\mathscr{L}$ as a Lie algebra, and so $D^{\prime}=0$, i.e., $D_{x}=\lambda \operatorname{ad}\left(e_{x}\right)$.

In the next lemma we determine the derivation $D_{0}$. By (3.2) we have

$$
D_{0}\left(e_{x}\right)=\mu(x) e_{x}, \quad x \in A
$$

where $\mu(x)=c(0, x)$.

Lemma 3.2. The map $\mu: A \rightarrow F$ is additive.
Proof. We have to show that

$$
\begin{equation*}
\mu(x+y)=\mu(x)+\mu(y) \tag{3.10}
\end{equation*}
$$

holds for all $x, y \in A$. If $\varphi(x, y) \neq 0$, this follows by applying $D_{0}$ to (1.1). Since $\mu(0)=c(0,0)=0$ by (3.4), it follows that (3.10) also holds if $x=0$ or $y=0$.

Now let $y=-x \neq 0$. Choose $z \in A$ such that $\varphi(x, z) \neq 0$. Then we have

$$
\mu(z)=\mu(z-x)+\mu(x)=\mu(z)+\mu(-x)+\mu(x) .
$$

Hence, $\mu(x)+\mu(-x)=0$, i.e., (3.10) holds also when $x+y=0$.

Finally, let $x, y, x+y \neq 0$ and $\varphi(x, y)=0$. We choose $z \in A$ such that $\varphi(x, z), \varphi(y, z)$, and $\varphi(x+y, z)$ are all nonzero. It follows that also $\ddot{\varphi}(x+z, y-z) \neq 0$. Hence, we can apply (3.10) to each of the pairs $(x+z, y-z),(x, z)$, and $(y,-z)$. So, we obtain that

$$
\mu(x+y)=\mu(x+z)+\mu(y-z)=\mu(x)+\mu(y)+\mu(z)+\mu(-z) .
$$

Since $\mu(z)+\mu(-z)=0,(3.10)$ is proved.

Let $\eta: A \rightarrow \operatorname{Hom}(A, F)$ be the map such that $\eta(x)(y)=\varphi(x, y)$ for all $x, y \in A$. Since $\varphi$ is non-degenerate, the homomorphism $\eta$ is injective. We denote by $\langle\eta(A)\rangle$ the $F$-subspace of $\operatorname{Hom}(A, F)$ spanned by the subgroup $\eta(A)$.

Lemma 3.3. If $\operatorname{dim}_{F}\langle\eta(A)\rangle=n<\infty$, then $D^{\prime}:=D-D_{0}$ is an inner derivation.

Proof. By (3.3) and Lemma 3.1 we have

$$
D^{\prime}=\sum_{x \neq 0} \lambda_{x} \operatorname{ad}\left(e_{x}\right)
$$

for some $\lambda_{x} \in F$. Let $B \subset A$ consist of all $x \neq 0$ such that $\lambda_{x} \neq 0$.
Choose $a_{1}, \ldots, a_{n} \in A$ such that their images under $\eta$ form a basis of $\langle\eta(A)\rangle$ over $F$. Let $B_{i}$ consist of all $x \in B$ such that $\varphi\left(x, a_{i}\right) \neq 0$. Since $c\left(x, a_{i}\right)=\lambda_{x} \varphi\left(x, a_{i}\right)$, the finiteness condition ( F ) implies that $B_{i}$ is a finite set.

Assume that there exists an $x \in B$ such that $x \notin B_{i}$ for all $i=1, \ldots, n$. Thus, $\varphi\left(x, a_{i}\right)=0$ for all $i$ 's. For arbitrary $y \in A$ there exist $t_{1}, \ldots, t_{n} \in F$ such that

$$
\eta(y)=t_{1} \eta\left(a_{1}\right)+\cdots+t_{n} \eta\left(a_{n}\right)
$$

It follows that

$$
\varphi(y, x)=\sum_{i=1}^{n} t_{i} \eta\left(a_{i}\right)(x)=\sum_{i=1}^{n} t_{i} \varphi\left(a_{i}, x\right)=0
$$

for all $y \in A$. As $\varphi$ is non-degenerate, we conclude that $x=0$. As $x \in B$, we have a contradiction.

Hence, we have shown that $B$ is the union of the $B_{i}$ 's, and so $B$ is a finite set. Consequently, $D^{\prime}$ is an inner derivation.

Proposition 3.4. Suppose that $\operatorname{rank}(A)<\infty$. If $D$ is a locally finite derivation of $\mathscr{L}$, then there exists $\mu \in \operatorname{Hom}(A, F)$ such that $D\left(e_{x}\right)=\mu(x) e_{x}$ for all $x$.

Proof. By (3.3) and Lemma 3.1, we have

$$
D=D_{0}+\sum_{x \neq 0} \lambda_{x} \operatorname{ad}\left(e_{x}\right)
$$

for some scalars $\lambda_{x} \in F$. By Lemma 3.3, the set $B=\left\{x \in A \backslash\{0\}: \lambda_{x} \neq 0\right\}$ is finite. Assume that $B$ is not empty. We can choose a total ordering " $\geq$ " on $A$, compatible
with its group structure, and such that the maximal element $u$ of $B$ is $>0$. Choose $z \in A$ such that $\varphi(u, z) \neq 0$. By induction on $k \geq 1$, it is easy to show that

$$
D^{k}\left(e_{z}\right)=\lambda_{u}^{k} \varphi(u, z)^{k} e_{z+k u}+v_{k},
$$

where $v_{k}$ is a linear combination of $e_{x}$ 's with $x<z+k u$. It follows that $D$ is not locally finite.

Hence, if $D$ is locally finite, then $B=\emptyset$ and so $D=D_{0}$. It remains to apply Lemma 3.2.

We do not know whether or not the restriction on the rank of $A$ can be removed from the above proposition.

Corollary 3.5. A simple Lie algebra $\mathscr{L}(A, \varphi)$ (with no restriction on the rank of $A$ ) is not isomorphic to any generalized Block algebra or simple generalized Witt algebra.

Proof. It follows from the proof of Proposition 3.4 that $\mathscr{L}(A, \varphi)$ has no ad-semisimple elements except 0 . On the other hand, all generalized Block algebras and simple generalized Witt algebras have non-trivial tori.

## 4. The isomorphism theorem

We shall determine all isomorphisms

$$
\begin{equation*}
\theta: \mathscr{L}(A, \varphi) \rightarrow \mathscr{L}(B, \psi) \tag{4.1}
\end{equation*}
$$

between two simple algebras $\mathscr{L}(A, \varphi)$ and $\mathscr{L}(B, \psi)$, assuming that $A$ and $B$ have finite ranks. Clearly, $\theta$ extends to an isomorphism, again denoted by $\theta$, of the Lie algebras $L(A, \varphi)$ and $L(B, \psi)$ by defining $\theta\left(e_{0}\right)=e_{0}$.

Theorem 4.1. The Lie algebra isomorphisms (4.1) are precisely the linear maps $\theta$ such that

$$
\begin{equation*}
\theta\left(e_{x}\right)=a \chi(x) e_{\sigma(x)}, \quad \forall x \in A \backslash\{0\} \tag{4.2}
\end{equation*}
$$

where $\chi \in \operatorname{Hom}\left(A, F^{*}\right), \sigma: A \rightarrow B$ is an isomorphism, and the constant $a \in F^{*}$ satisfies

$$
\begin{equation*}
\varphi(x, y)=a \psi(\sigma(x), \sigma(y)), \quad \forall x, y \in A \tag{4.3}
\end{equation*}
$$

Proof. Assume that the map (4.1) is an isomorphism of Lie algebras. For every $\mu \in \operatorname{Hom}(A, F)$, the linear map $D_{\mu}: \mathscr{L}(A, \varphi) \rightarrow \mathscr{L}(A, \varphi)$ defined by

$$
D_{\mu}\left(e_{x}\right)=\mu(x) e_{x}, \quad x \in A \backslash\{0\}
$$

is a derivation of degree 0 (with respect to the $A$-gradation of $\mathscr{L}(A, \varphi)$ ).
By Proposition 3.1 we know that the derivations $D_{\mu}$ are exactly the locally finite derivations of $\mathscr{L}(A, \varphi)$. Furthermore, the vectors $e_{x}, x \in A$, are the only common
eigenvectors (up to scalar multiple) of all $D_{\mu}$ 's. Analogous statements are of course valid for $\mathscr{L}(B, \psi)$. Consequently, there is a bijection $\sigma: A \rightarrow B$ such that

$$
\theta\left(e_{x}\right)=c_{x} e_{\sigma(x)}, \quad x \in A
$$

for some scalars $c_{x} \in F^{*}$. Clearly, $\sigma(0)=0$.
By applying $\theta$ to (1.1) we obtain

$$
\begin{equation*}
c_{x+y} \varphi(x, y) e_{\sigma(x+y)}=c_{x} c_{y} \psi(\sigma(x), \sigma(y)) e_{\sigma(x)+\sigma(y)} \tag{4.4}
\end{equation*}
$$

If $\varphi(x, y) \neq 0$, we derive that

$$
\begin{equation*}
\sigma(x+y)=\sigma(x)+\sigma(y) \tag{4.5}
\end{equation*}
$$

Let $x \neq 0$ and choose $y \in A$ such that $\varphi(x, y) \neq 0$. By (4.5) we have

$$
\sigma(y)=\sigma(x)+\sigma(y-x)=\sigma(x)+\sigma(y)+\sigma(-x)
$$

Consequently, (4.5) also holds for $y=-x$.
Obviously, (4.5) holds if $x=0$ or $y=0$. Assume now that $x \neq 0, y \neq 0$, while $\varphi(x, y)=0$. We choose $z \in A$ such that the numbers $\varphi(x, z), \varphi(y, z)$, and $\varphi(x+y, z)$ are all nonzero. Then we can apply (4.5) to each of the pairs $(x-z, y+z),(x,-z)$, and $(y, z)$. So, we obtain that

$$
\sigma(x+y)=\sigma(x-z)+\sigma(y+z)=\sigma(x)+\sigma(-z)+\sigma(y)+\sigma(z)
$$

As $\sigma(z)+\sigma(-z)=0$, we infer that (4.5) holds also for the pair $(x, y)$.
Hence we have shown that $\sigma: A \rightarrow B$ is a homomorphism, and consequently an isomorphism.

Eq. (4.4) now implies that

$$
\begin{equation*}
\epsilon_{x+y} \varphi(x, y)=\epsilon_{x} c_{y} \psi(\sigma(x), \sigma(y)) \tag{4.6}
\end{equation*}
$$

holds for all $x, y \in A$.
We claim that the ratio

$$
\begin{equation*}
\lambda=\frac{\psi(\sigma(x), \sigma(y))}{\varphi(x, y)} \tag{4.7}
\end{equation*}
$$

is independent of $x$ and $y$. Of course, we have to assume that $\varphi(x, y) \neq 0$, and so, by (4.6), also $\psi(\sigma(x), \sigma(y)) \neq 0$.

By replacing $x$ with $2 x$ in (4.6) we obtain that

$$
c_{2 x+y} \varphi(x, y)=c_{2 x} c_{y} \psi(\sigma(x), \sigma(y))
$$

By replacing $y$ with $x+y$ in (4.6), we obtain that

$$
c_{2 x+y} \varphi(x, y)^{2}=c_{x}^{2} c_{y} \psi(\sigma(x), \sigma(y))^{2}
$$

The above two equations imply that $\lambda=c_{2 x} c_{x}^{-2}$. Since the expression (4.7) is symmetric in $x$ and $y$, we also have $\lambda=c_{2 y} c_{y}^{-2}$. Hence, we have shown that

$$
\begin{equation*}
c_{2 x} c_{x}^{-2}=c_{2 y} c_{y}^{-2} \tag{4.8}
\end{equation*}
$$

if $\varphi(x, y) \neq 0$. The restriction $\varphi(x, y) \neq 0$ can easily be removed, i.e., (4.8) holds for all nonzero $x$ and $y$. In particular, our claim is proved.

If $a=\lambda^{-1}$, then (4.6) shows that

$$
\begin{equation*}
a \cdot c_{x+y}=c_{x} c_{y} \tag{4.9}
\end{equation*}
$$

holds whenever $\varphi(x, y) \neq 0$.
Suppose that $x, y, x+y \neq 0$ while $\varphi(x, y)=0$. Choose $z \in A$ such that the numbers $\varphi(x, z), \varphi(y, z)$, and $\varphi(x-y, z)$ are all nonzero. We can apply (4.9) to each of the pairs $(x+z,-z),(x, z),(y,-z)$, and $(x+z, x-z)$.

Hence, we have

$$
a^{2} c_{x}=a c_{x+z} c_{-z}=c_{x} c_{z} c_{-z}
$$

and

$$
a^{3} c_{x+y}=a^{2} c_{x+z} c_{y-z}=c_{x} c_{z} c_{y} c_{-z}
$$

Consequently, (4.9) holds whenever $x, y, x+y \neq 0$.
If we define $\chi: A \rightarrow F^{*}$ by $\chi(0)=1$ and $\chi(x)=\lambda c_{x}$ for $x \neq 0$, then (4.9) implies that $\chi$ is a homomorphism. Furthermore, (4.2) and (4.3) hold.

The converse is straightforward.
We now apply Theorem 4.1 to obtain a description of the automorphism group of $\mathscr{L}=\mathscr{L}(A, \varphi)$, assuming that $A$ has finite rank. Every character $\chi \in \operatorname{Hom}\left(A, F^{*}\right)=X(A)$ determines an automorphism $\theta_{\chi}$ of $\mathscr{L}$ by

$$
\theta_{\chi}\left(e_{x}\right)=\chi(x) e_{x}, \quad x \neq 0
$$

The map $\chi \mapsto \theta_{\chi}$ is an injective homomorphism $X(A) \rightarrow \operatorname{Aut}(\mathscr{L})$ and we shall identify the character group $X(A)$ of $A$ with its image in $\operatorname{Aut}(\mathscr{L})$.

Let $\mathscr{A}=\mathscr{A}(\mathscr{L})$ be the subgroup of $\operatorname{Aut}(A)$ consisting of all automorphisms $\sigma$ of $A$ for which there is a constant $a_{\sigma} \in F^{*}$ such that

$$
\begin{equation*}
\varphi(\sigma(x), \sigma(y))=a_{\sigma} \varphi(x, y), \quad \forall x, y \in A . \tag{4.10}
\end{equation*}
$$

Clearly, such constant $a_{\sigma}$ is unique.
Each $\sigma \in \mathscr{A}$ determines an automorphism $\theta_{\sigma}$ of $\mathscr{L}$ by

$$
\theta_{\sigma}\left(e_{x}\right)=a_{\sigma}^{-1} e_{\sigma(x)}, \quad x \neq 0
$$

The homomorphism sending $\sigma \mapsto \theta_{\sigma}$ is injective and we identify $\mathscr{A}$ with its image in $\operatorname{Aut}(\mathscr{L})$.

The following corollary follows immediately from Theorem 4.1.
Corollary 4.2. If $\mathscr{L}=\mathscr{L}(A, \varphi)$ is simple and $\operatorname{rank}(A)<\infty$, then

$$
\operatorname{Aut}(\mathscr{L})=X(A) \rtimes \mathscr{A}(\mathscr{L})
$$

(semidirect product, with $X(A)$ normal in $\operatorname{Aut}(\mathscr{L})$ ).

Example 2. Let $A=\mathbf{Z}^{2}$ and let $e_{1}=(1,0)$ and $e_{2}=(0,1)$ be the standard basis vectors. A bi-additive skew-symmetric map $\varphi: A \times A \rightarrow F$ is uniquely determined by the scalar $\alpha=\varphi\left(e_{1}, e_{2}\right) \in F$. We shall write $\varphi_{\alpha}$ for this $\varphi$. Clearly, $\varphi_{\alpha}$ is nondegenerate if and only if $\alpha \neq 0$. We set

$$
\mathscr{L}_{x}:=\mathscr{L}\left(\mathbf{Z}^{2}, \varphi_{x}\right), \quad \alpha \neq 0 .
$$

If $\alpha \beta \neq 0$, then the linear map $\theta: \mathscr{L}_{\alpha} \rightarrow \mathscr{L}_{\beta}$ defined by $\theta\left(e_{x}\right)=\alpha \beta^{-1} e_{x}, x \in \mathbf{Z}^{2} \backslash\{0\}$ is an isomorphism of Lie algebras. Hence, in the case $A=\mathbf{Z}^{2}$, there is only one (up to isomorphism) simple Lie algebra $\mathscr{L}\left(\mathbf{Z}^{2}, \varphi\right)$.

Assume now that $\varphi=\varphi_{1}$, i.e., $\varphi\left(e_{1}, e_{2}\right)=1$. We claim that $\mathscr{A}(\mathscr{L})=\mathrm{GL}_{2}(\mathbf{Z})$ holds in this case. A simple computation shows that if

$$
\sigma=\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right) \in \mathrm{GL}_{2}(\mathbf{Z}), \quad J=\left(\begin{array}{rr}
0 & 1 \\
-1 & 0
\end{array}\right)
$$

then $\sigma^{\prime} J \sigma=\operatorname{det}(\sigma) J$, where $\sigma^{\prime}$ is the transpose of $\sigma$. Hence, (4.10) holds with $a_{\sigma}=$ $\operatorname{det}(\sigma)= \pm 1$. This proves our claim.

Consequently, $\operatorname{Aut}(\mathscr{L}) \simeq X\left(\mathbf{Z}^{2}\right) \rtimes \mathrm{GL}_{2}(\mathbf{Z})$.

## 5. Computation of $H^{2}(\mathscr{L}, F)$

In this section we compute the second cohomology group $H^{2}(\mathscr{L}, F)$ of the simple Lie algebra $\mathscr{L}=\mathscr{L}(A, \varphi)$.

Let $\psi: \mathscr{L} \times \mathscr{L} \rightarrow F$ be an arbitrary 2-cocycle, i.e., a skew-symmetric bilinear form satisfying the identity

$$
\begin{equation*}
\psi([u, v], w) \mid \psi([v, w], u)+\psi([w, u], v)=0 . \tag{5.1}
\end{equation*}
$$

We set

$$
\begin{equation*}
\lambda(x, y)=\psi\left(e_{x}, e_{y}\right) \tag{5.2}
\end{equation*}
$$

for $x, y \neq 0$. By setting $u=e_{x}, v=e_{y}, w=e_{z}$ in (5.1), we obtain that

$$
\begin{equation*}
\varphi(x, y) \lambda(x+y, z)+\varphi(y, z) \lambda(y+z, x)+\varphi(z, x) \lambda(z+x, y)=0 \tag{5.3}
\end{equation*}
$$

holds for $x, y, z \neq 0$. If $x+y=0$, then $\lambda(x+y, z)$ is not defined. In that case $\varphi(x, y)=0$ and the first term in (5.3) should be interpreted as 0 . Similar interpretations should be used for the second and third terms if $y+z=0$ and $z+x=0$, respectively.

Since $\psi$ is skew-symmetric, it follows from (5.2) that

$$
\begin{equation*}
\lambda(x, y)+\lambda(y, x)=\mathbf{0} . \tag{5.4}
\end{equation*}
$$

For $u \in A$ define $\lambda_{u}(x)=\lambda(x, u-x)$ for $x \neq 0, u$. From (5.4) we deduce that

$$
\begin{equation*}
\lambda_{u}(u-x)=-\lambda_{u}(x), \quad x \neq 0, u . \tag{5.5}
\end{equation*}
$$

By setting $z=u-x-y$ in (5.3), we obtain that

$$
\begin{equation*}
\varphi(x, y)\left[\lambda_{u}(x+y)-\lambda_{u}(x)-\lambda_{u}(y)\right]-\varphi(y, u) \lambda_{u}(x)-\varphi(u, x) \lambda_{u}(y)=0 \tag{5.6}
\end{equation*}
$$

holds for $x, y \neq 0$ and $x+y \neq u$.
Assume that $u \neq 0$. By setting $y=2 x$ in (5.6), we obtain that

$$
\begin{equation*}
\lambda_{u}(2 x)=2 \lambda_{u}(x) \tag{5.7}
\end{equation*}
$$

holds if $\varphi(u, x) \neq 0$.
If $\varphi(u, x), \varphi(u, y)$, and $\varphi(u, x+y)$ are all nonzero, then by replacing $x$ and $y$ in (5.6) with $2 x$ and $2 y$, respectively, and by using (5.7), we obtain that

$$
\begin{equation*}
\varphi(x, y)\left[\lambda_{u}(x+y)-\lambda_{u}(x)-\lambda_{u}(y)\right]=0 \tag{5.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\varphi(u, x) \lambda_{u}(y)=\varphi(u, y) \lambda_{u}(x) \tag{5.9}
\end{equation*}
$$

If $\varphi(u, x), \varphi(u, y) \neq 0$ and $\varphi(u, x+y)=0$ then $\varphi(u, x+2 y) \neq 0$ and so (5.9) is valid if we replace $y$ with $2 y$. By invoking (5.7), we conclude that (5.9) is valid as written.

It follows from (5.9) that the ratio

$$
a_{u}=\frac{\lambda_{u}(x)}{\varphi(u, x)}
$$

is independent of $x$, provided that $\varphi(u, x) \neq 0$. In other words, there is a constant $a_{u} \in F$ such that

$$
\begin{equation*}
\lambda_{u}(x)=a_{u} \varphi(u, x) \tag{5.10}
\end{equation*}
$$

holds whenever $\varphi(u, x) \neq 0$.
Let $x \neq 0, u$ and $\varphi(u, x)=0$. Choose $y \in A$ such that $\varphi(x, y)$ and $\varphi(u, y)$ are both nonzero. By replacing $x$ in (5.8) with $x-y$, we infer that

$$
\lambda_{u}(x)=\lambda_{u}(x-y)+\lambda_{u}(y)=a_{u}[\varphi(u, x-y)+\varphi(u, y)]=0 .
$$

Hence, (5.10) is valid for all $x \neq 0, u$.
Let $l: \mathscr{L} \rightarrow F$ be the linear function defined by $l\left(e_{x}\right)=a_{x}$ for $x \neq 0$. Let $\tilde{\psi}$ be the 2-cocycle defined by

$$
\tilde{\psi}(u, v)=\psi(u, v)+l([u, v])
$$

If $x, y, x+y \neq 0$, then we have

$$
\tilde{\psi}\left(e_{x}, e_{y}\right)=\lambda(x, y)+\varphi(x, y) a_{x+y}=\lambda_{x+y}(x)-a_{x+y} \varphi(x+y, x)=0
$$

Hence, by replacing $\psi$ with the cohomologous 2-cocycle $\tilde{\psi}$, we may assume that $\lambda_{u}=0$ for all $u \neq 0$.

It remains to determine $\lambda_{0}$. For $u=0$, (5.6) becomes

$$
\varphi(x, y) \cdot\left[\lambda_{0}(x+y)-\lambda_{0}(x)-\lambda_{0}(y)\right]=0 .
$$

Hence,

$$
\begin{equation*}
\lambda_{0}(x+y)=\lambda_{0}(x)+\lambda_{0}(y) \tag{5.11}
\end{equation*}
$$

holds if $\varphi(x, y) \neq 0$.
Now assume that $x, y, x+y \neq 0$ while $\varphi(x, y)=0$. We choose $z \in A$ such that the numbers $\varphi(x, z), \varphi(y, z)$, and $\varphi(x+y, z)$ are all nonzero. Then we have

$$
\begin{aligned}
\lambda_{0}(x+y) & =\lambda_{0}(x+z)+\lambda_{0}(y-z) \\
& =\lambda_{0}(x)+\lambda_{0}(y)+\lambda_{0}(z)+\lambda_{0}(-z)
\end{aligned}
$$

and

$$
\lambda_{0}(x)=\lambda_{0}(x+z)+\lambda_{0}(-z)=\lambda_{0}(x)+\lambda_{0}(z)+\lambda_{0}(-z) .
$$

Consequently, (5.11) holds whenever $x, y, x+y \neq 0$.
Let $\mu: A \rightarrow F$ be defined by $\mu(x)=\lambda_{0}(x)$ if $x \neq 0$ and $\mu(0)=0$. It follows from (5.11) that $\mu \in \operatorname{Hom}(A, F)$.

Hence, we have proved the following result.
Theorem 5.1. For the simple Lie algebra $\mathscr{L}=\mathscr{L}(A, \varphi), H^{2}(\mathscr{L}, F)$ is spanned by the cohomology classes $\left[\psi_{\mu}\right]$ where $\mu \in \operatorname{Hom}(A, F)$ and the 2 -cocycle $\psi_{\mu}$ is defined by

$$
\psi_{\mu}\left(e_{x}, e_{y}\right)=\delta_{x+y, 0} \mu(x), \quad x, y \neq 0
$$

## References

[1] A.A. Albert and M.S. Frank, Simple Lie algebras of characteristic $p$, Univ. Politec. Torino Rend. Sem. Mat. 14 (1954 55) 117139.
[2] R. Block, On torsion-free abelian groups and Lie algebras, Proc. Amer. Math. Soc. 9 (1958) 613-620.
[3] R. Block, New simple Lie algebras of prime characteristic, Trans. Amer. Math. Soc. 89 (1958) 421-449.
[4] D.Ž. Đoković and K. Zhao, Derivations, isomorphisms, and second cohomology of generalized Block algebras, Algebra Colloq. 3 (1996) 245-272.
[5] D.Z.. Đoković and K. Zhao, Some simple subalgebras of generalized Block algebras, J. Algebra, to appear.
[6] D.Z.. Đoković and K. Zhao, Derivations, isomorphisms, and second cohomology of generalized Witt algebras, Trans. Amer. Math. Soc., to appear.
[7] W.P. Kocpp, Simple homogeneous subalgebras of generalized Witt algebras of finite rank, Ph.D. Thesis, University of Wisconsin, Madison, 1995.


[^0]:    * Corresponding author. E-mail: dragomir@herod.uwaterloo.ca. Supported in part by the NSERC Grant A-5285.
    ${ }^{1}$ Supported by Academia Sinica of People's Republic of China.

